

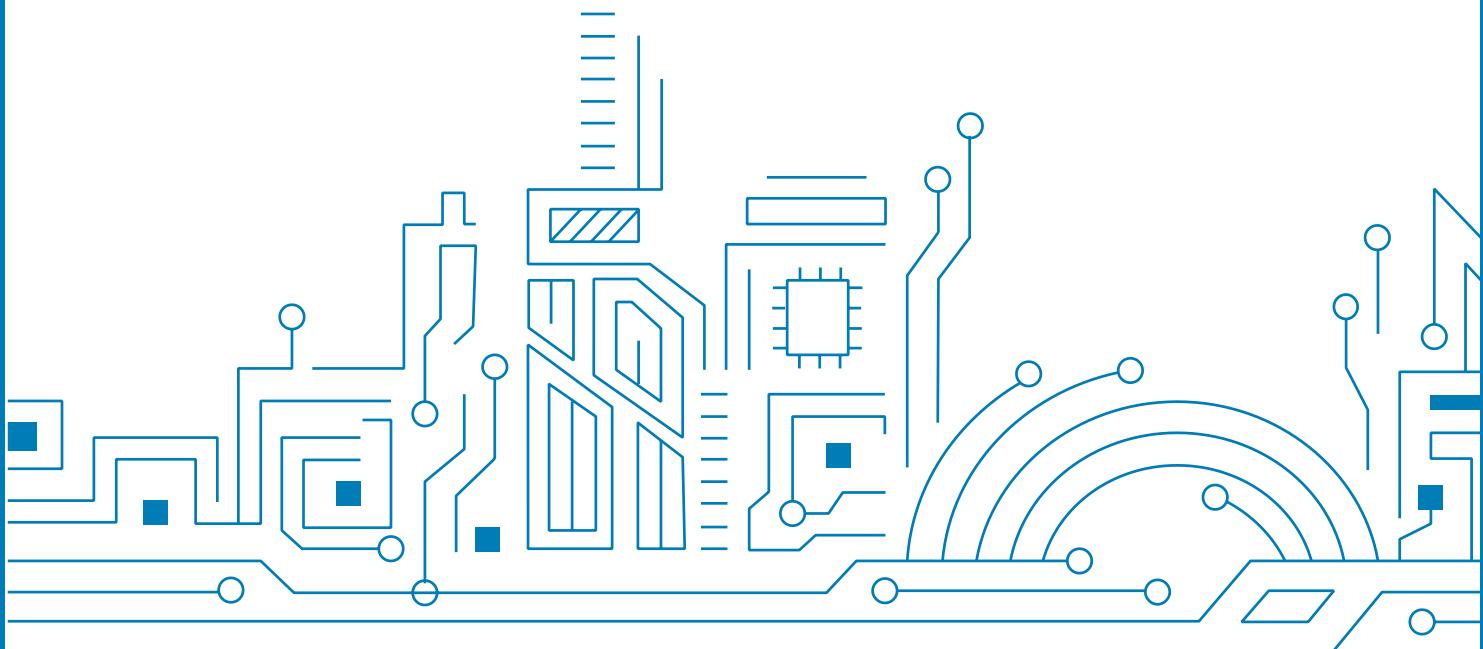


ALLYSTAR

# Multi-System GNSS Positioning Module

## TAU1105

Datasheet V1.2



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## 1 SYSTEM OVERVIEW

### 1.1 Overview

TAU1105 is a multi-system GNSS positioning module, which is based on the state of art CYNOSURE III architecture. It supports BDS-3 (BeiDou Navigation Satellite System 3). Besides, it is capable of tracking most of the global civil navigation systems (BDS, GPS, GLONASS, Galileo, QZSS and SBAS).

TAU1105 integrates efficient power management architecture, while providing high sensitivity and low power GNSS solutions which make it suitable for navigation applications on automotive and consumer electronics, and fleet management.

### 1.2 Features

- Concurrent reception of GPS, BDS, GLONASS, Galileo, QZSS and SBAS
- High sensitivity design and low power management
- Smart jammer detection and suppression
- Highly integrated labelling module, the best cost-effective GNSS solution

### 1.3 Module Photo

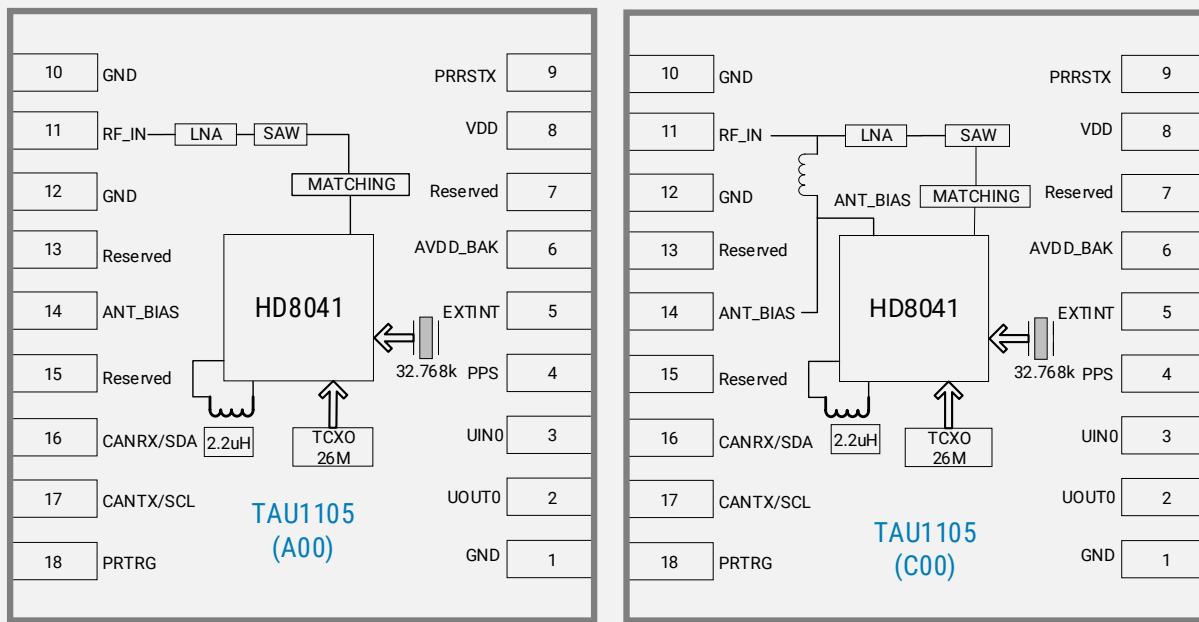


**Figure 1 TAU1105 module photo**

**Table 1 Differences between TAU1105-1010A00 and TAU1105-1010C00**

PN	Description
TAU1105-1010A00	RF_IN pin does not provide the power for active antenna, so a bias choke from ANT_BIAS to RF_IN pin should be used.
TAU1105-1010C00	A bias choke is built-in between ANT_BIAS and RF_IN pin to power the active antenna. If the active antenna is powered by a supply source other than the module, a capacitor should be used to block the DC from RF_IN.

## 1.4 Block Diagram



**Figure 2 Block diagram**

## 1.5 Specifications

**Table 2 Specifications**

Parameter	Specification	
GNSS Tracking channel	40 channels	
GNSS reception	GPS/QZSS: L1C/A BDS: B1I, B1C <sup>[1]</sup> GLONASS: L1OF Galileo: E1 SBAS	
Update rate	Maximum 10Hz	
Position accuracy <sup>[2]</sup>	GNSS	2.5m CEP
Velocity & Time accuracy	GNSS	0.1m/s CEP
	1PPS	20ns
Time to First Fix (TTFF)	Hot start	1 sec
	Cold start	28 secs
Sensitivity	Cold start	-148dBm
	Hot start	-155dBm
	Reacquisition	-158dBm
	Tracking & navigation	-162dBm
Operating limit	Velocity	515 m/s
	Altitude	18,000 m
Safety supervision	Antenna short circuit protection	

Parameter	Specification	
	Low voltage detection	
Serial interface	UART	1
	I2C	1
Protocol	NMEA 0183 Protocol Ver. 4.00/4.10, Cynosure GNSS Receiver Protocol	
Operating condition	Main voltage	1.8 ~ 3.6V
	Digital I/O voltage	1.8 ~ 3.6V
	Backup voltage	1.8 ~ 3.6V
Power consumption	GPS+QZSS	25mA@3.3V
	GNSS	35mA@3.3V
	Standby	12uA
Operating temperature	-40 °C ~ +85 °C	
Storage temperature	-40 °C ~ +85 °C	
Package	10.1mm x 9.7mm x 2.5mm 18-pin stamp hole	
Certification	RoHS & REACH	

\* [1] Supported by customized firmware.

\* [2] Open sky, demonstrated with a good external LNA

## 2 PIN DESCRIPTION

### 2.1 Pin Assignment



Figure 3 Pin assignment (top view)

## 2.2 Detailed Pin Descriptions

**Table 3 Detailed pin descriptions**

Function	Symbol	No.	I/O	Description
Power	VDD	8	Power	Main supply input.
	GND	1,10,12	VSS	Ground
	AVDD_BAK	6	Power	Backup supply input.
Antenna	RF_IN	11	I	RF signal input. Use a controlled impedance of 50Ω for the routing from RF_IN pin to the antenna or the antenna connector.
	ANT_BIAS	14	O	RF section output voltage. Used to power the external active antenna. The current is limited below 35mA.
UART	UOUT0	2	O	UART0 serial data output.
	UIN0	3	I	UART0 serial data input.
I <sup>2</sup> C/CAN	CANRX/SDA	16	I/O	I <sup>2</sup> C data transmission or CAN data input. Leave it floating if not used.
	CANTX/SCL	17	I/O	I <sup>2</sup> C clock, or CAN data output. Leave it floating if not used.
System	PRTRG	18	I	Mode selection, or the trigger input in deep sleep mode to wake up the system
	PRRSTX	9	I	External reset, low active
	PPS	4	O	Setting for time pulse output(PPS)
	EXTINT	5	I	GPIO, Default (EXTINT): a trigger pin to external interrupt, leave it floating if not used.
Reserved	Reserved	7,13,15,	--	Reserved, leave it floating if not used

### 3 ELECTRICAL CHARACTERISTICS

#### 3.1 Absolute Maximum Rating

**Table 4 Absolute rating**

Symbol	Parameter	Min.	Max.	Unit
VDD	Power input for the main power domain	-0.5	3.63	V
AVDD_BAK	Power input for the backup power domain	-0.5	3.63	V
T <sub>storage</sub>	Storage temperature	-40	85	°C
T <sub>solder</sub>	Solder reflow temperature	--	260	°C

#### 3.2 IO Characteristics

##### 3.2.1 PRRSTX and PRTRG

**Table 5 PRRSTX and PRTRG**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
I <sub>IZ</sub>	Input leakage current	--	--	--	+/-1	uA
V <sub>IH</sub>	Input high voltage	--	AVDD_BAK*0.7	--	AVDD_BAK	V
V <sub>IL</sub>	Input low voltage	--	0	--	AVDD_BAK*0.3	V
C <sub>i</sub>	Input capacitance	--	--	--	10	pF
R <sub>PU</sub>	Pull-up resistance	--	18	--	84	KΩ

##### 3.2.2 ANT\_BIAS

**Table 6 ANT\_BIAS**

Parameter	Condition	Min.	Typ.	Max.	Unit
RF supply current	--	--	--	35	mA
RF supply voltage	--	1.42	--	3.43	V

##### 3.2.3 Others

**Table 7 Others**

Symbol	Parameter	Condition	Min.	Typ.	Max.	Unit
I <sub>IZ</sub>	Input leakage current	--	--	--	+/-1	uA
V <sub>IH</sub>	Input high voltage	--	VDD*0.7	--	VDD	V
V <sub>IL</sub>	Input low voltage	--	0	--	VDD*0.3	V
V <sub>OH</sub>	Output high voltage	I <sub>OH</sub> =11.9 mA, VDD=3.3V	2.64	--	--	V
		I <sub>OH</sub> =2.8 mA, VDD=1.8V	1.53	--	--	V
V <sub>OL</sub>	Output low voltage	I <sub>OL</sub> =7.9 mA, VDD=3.3V	--	--	0.4	V
		I <sub>OL</sub> =3.9 mA, VDD=1.8V	--	--	0.45	V
C <sub>i</sub>	Input capacitance	--	--	--	11	pF
R <sub>PU</sub>	Pull-up resistance	-	35	--	84	KΩ

### 3.3 DC Characteristics

#### 3.3.1 Operating Conditions

**Table 8** Operating conditions

Symbol	Parameter	Min.	Typ.	Max.	Unit
VDD	Power input for the main power domain	1.8	3.3	3.6	V
AVDD_BAK	Power input for the backup power domain	1.8	3.3	3.6	V
ICC <sub>max</sub>	Maximum operating current @ VDD	--	--	200	mA
T <sub>env</sub>	Operating temperature	-40	--	85	°C

#### 3.3.2 Power Consumption

**Table 9** Power consumption

Symbol	Parameter	Measure Pin	Typ.	Unit
I <sub>CCRX1</sub> <sup>[1]</sup>	Run Mode (GPS+QZSS)	VDD <sup>[3]</sup>	25	mA
I <sub>CCRX2</sub> <sup>[2]</sup>	Run Mode (GNSS)	VDD <sup>[3]</sup>	35	mA
I <sub>CCDBM</sub>	Standby mode	AVDD_BAK <sup>[4]</sup>	12	uA

\* [1] GPS+QZSS, 16 tracking channels, position fixed

\* [2] GNSS, 32 tracking channels, position fixed

\* [3] Condition: VDD=3.3V@Room Temperature; All Pins Open.

\* [4] Condition: AVDD\_BAK=3.3V@Room Temperature; All Pins Open.

## 4 HARDWARE DESCRIPTION

### 4.1 Connecting Power

TAU1105 positioning module has two power supply pins: VDD and AVDD\_BAK. The VDD pin provides the main supply voltage, and the AVDD\_BAK pin provides the backup supply voltage. In order to ensure the positioning performance, please control the ripple of the module power supply. It is recommended to use the LDO above 200mA.

If the power for VDD pin is off, the real-time clock (RTC) and battery backed RAM (BBR) are supplied through the AVDD\_BAK pin. Thus, orbit information and time can be maintained and will allow a Hot or Warm start. If no backup battery is connected, the module performs a cold start at every power up if no aiding data are sent to the module.

*Note: If no backup supply is available, leave AVDD\_BAK pin floating.*

### 4.2 Antenna Design

There is built-in LNA and SAW in the GNSS module. It is recommended to use an active antenna with gain less than 36dB and the noise figure less than 1.5dB.

The module has built-in short circuit detection and open circuit detection function, which can detect the status of normal connection, and send out antenna status prompt message in NMEA data.

- Short circuit protection
  - » The module includes internal short circuit antenna detection. Once an overcurrent is detected at the ANT\_BIAS port, the module will cut off this power supply automatically to prevent permanent damages.
- Open circuit detection
  - » The module can detect an open circuit in the antenna. Users can judge it from antenna status messages.

Table 10 ANT\_BIAS current range and antenna status

Antenna status	Status output	ANT_BIAS current range
Open circuit	OPEN	0< ANT_BIAS ≤ 1mA
Regular circuit or open circuit	OK or OPEN	1mA< ANT_BIAS ≤ 2mA
Regular circuit	OK	2mA< ANT_BIAS ≤ 40±5mA <sup>[1]</sup>
Short circuit	SHORT	40±5mA <sup>[1]</sup> < ANT_BIAS < 55mA

\* [1] ±5mA are differences between product batches.

#### TIPs:

1. Pulse width of the minimum detectable overshoot current should be more than 10uS.
2. NMEA message of antenna status output:
  - OPEN: \$GNTXT,01,01,01,ANT\_OPEN\*40
  - OK: \$GNTXT,01,01,01,ANT\_OK\*50
  - SHORT: \$GNTXT,01,01,01,ANT\_SHORT\*06

## 4.3 Reset and Mode Control

The operation mode of GNSS module is controlled by PRRSTX (nRESET) and PRTRG (BOOT) pin. While the module works in normal operation, leave PRRSTX and PRTRG pins floating if there is no upgrading or reset demands, or others.

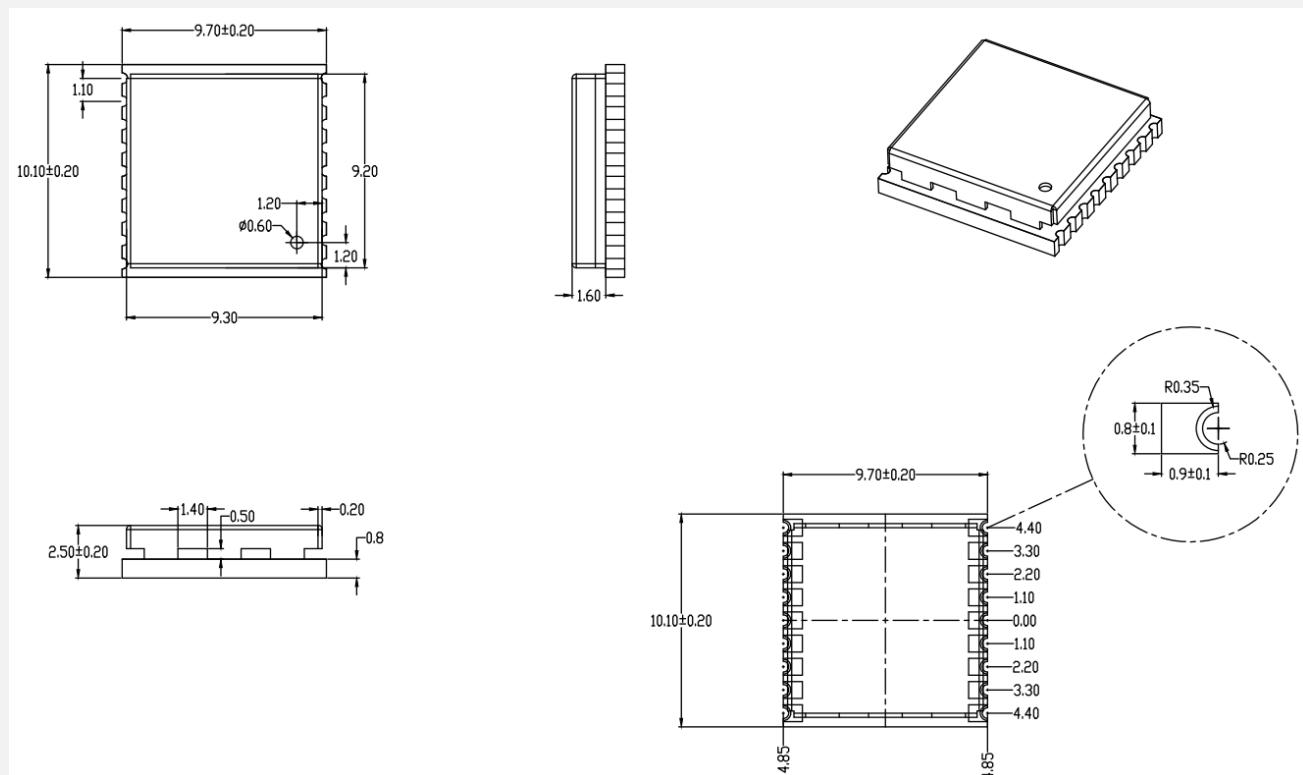
- Keep PRTRG pin floating during system power-up or the external reset (PRRSTX from low to high), and the module will enter **User Normal Mode**.
- When the module powers up or PRRSTX from low to high, the module will execute an **external reset**. (If the power for AVDD\_BAK is always on, the external reset will not affect the ephemeris data in the backup domain)
- Drive PRTRG pin to low or connect PRTRG to GND directly (not by pull-down resistance) during system power-up or the external reset (PRRSTX from low to high), and the system enters **BootROM Command Mode** at PRTRG pin being released from low to floating state, and ready for firmware upgrading command.
- When connecting PRRSTX and PRTRG to any host IO, DO NOT use the pull-up or pull-down resistance.

## 4.4 Serial Interfaces

The module provides a TTL Universal Asynchronous Receiver / Transmitter (UART) interface. The data format is: 1 start bit, 8 data bits, 1 stop bit, no checksum, and the default baud rate is 115200 bps. NMEA data outputs while the module is powered on.

When the module is applied to the specific application, users can shut off the main power in order to further reduce the power consumption. To avoid the high level in serial interface influencing the normal operation, it is highly suggested to cut off the serial port when shut off the main power. Otherwise, please set the serial port to input mode or high impedance state with pull-down resistor.

## 5 MECHANICAL SPECIFICATION



**Figure 4 Dimensions**

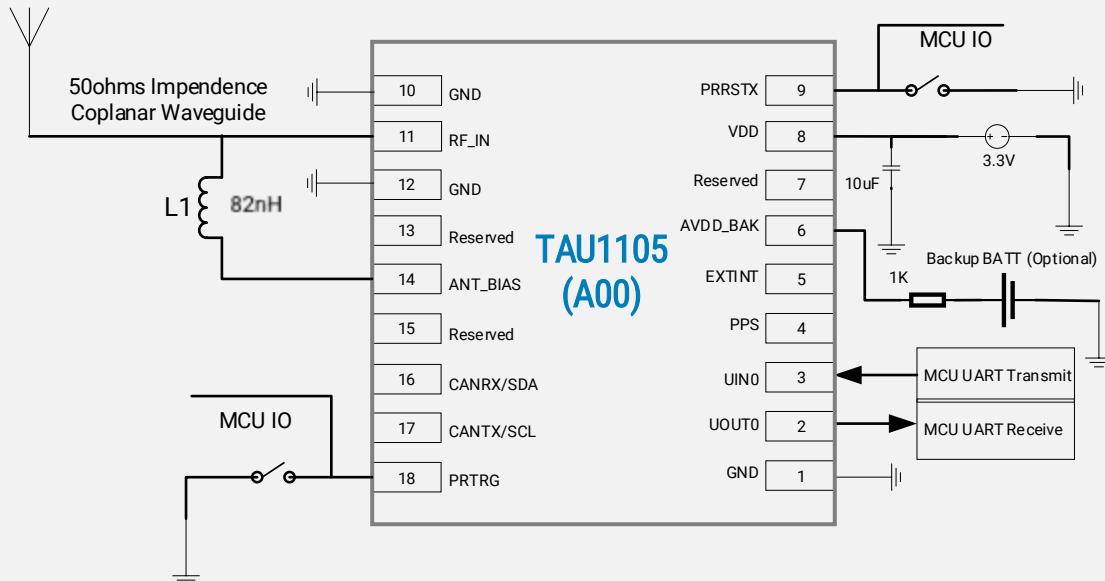
## 6 REFERENCE DESIGN

### 6.1 Minimal design

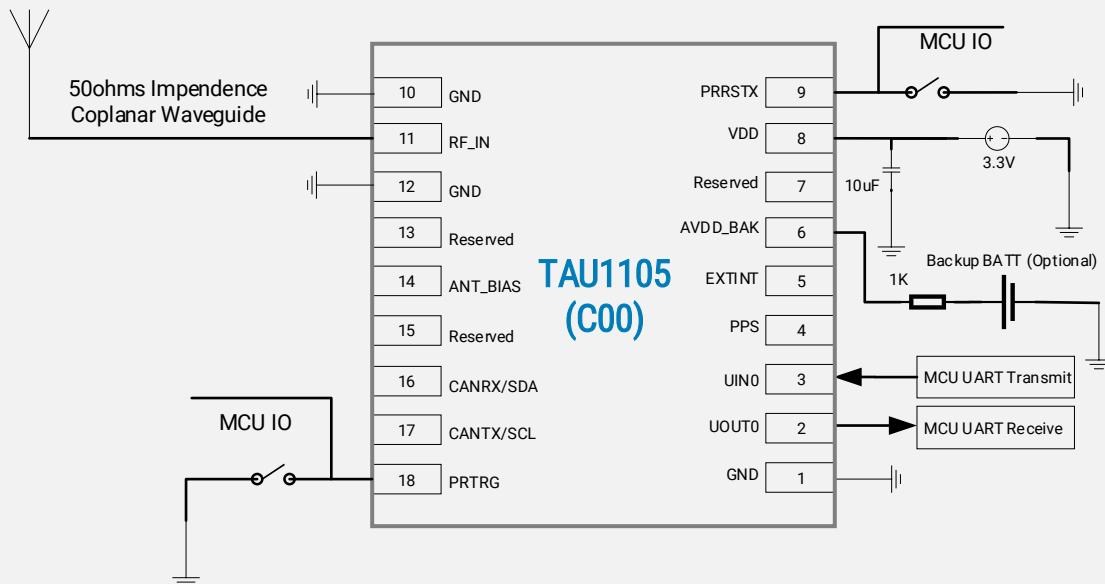
TAU1105 includes two designs of TAU1105 (A00) and TAU1105 (C00).

- In A00 design, RF\_IN pin does not provide the power for active antenna, so a bias choke of 82nH from ANT\_BIAS to RF\_IN pin should be used. (Refer to **Figure 5**)
- In C00 design, a bias choke is built-in between ANT\_BIAS and RF\_IN pin to power the active antenna. (Refer to **Figure 6**)
- If the active antenna is powered by a supply source other than the module, a capacitor should be used to block the DC from RF\_IN. (Refer to **Figure 7**)

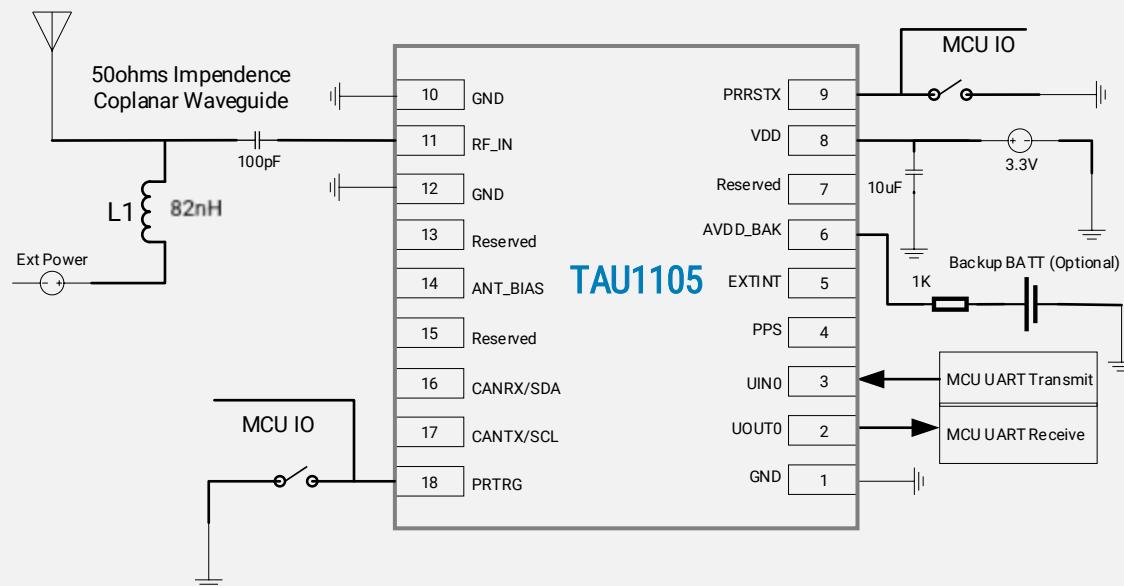
The characteristic impedance from RF\_IN pin to the antenna connector should be 50Ω.



**Figure 5 Minimal application diagram of A00 with internal power for ANT**

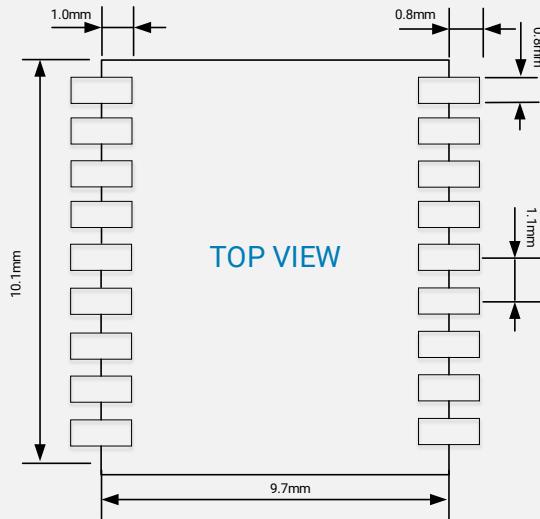


**Figure 6 Minimal application diagram of C00 with internal power for ANT**



**Figure 7 Minimal application diagram with external power for ANT**

## 6.2 PCB Footprint Reference



**Figure 8 PCB Footprint Reference**

## 6.3 Layout Notes

- 1) A decoupling capacitor should be placed close to VDD pin of the module, and the width of power routing should be more than 0.5mm;
- 2) The characteristic impedance of RF routing between RF port to antenna should be controlled to  $50 \Omega$ .
- 3) Do not place the module close to any EMI source, like antenna, RF routing, DC/DC or power conductor, clock signal or other high-frequency switching signal, etc.

### 6.3.1 Reflow soldering

**Table 11 Reflow profile features**

Profile Feature	Pb-Free Assembly
<b>Preheat/Soak</b>	
Temperature Min ( $T_{smin}$ )	150 °C
Temperature Max ( $T_{smax}$ )	200 °C
Time ( $t_s$ ) from ( $T_{smin}$ to $T_{smax}$ )	60-120s
<b>Ramp-up rate (<math>T_L</math> to <math>T_p</math>)</b>	3 °C/second max.
Liquidous temperature ( $T_L$ )	217 °C
Time ( $t_L$ ) maintained above $T_L$	60-150s
Peak package body temperature ( $T_p$ )	must not exceed the Classification temp $T_c^{[1]}$
Time ( $t_p$ )* within 5 °C of the specified classification temperature ( $T_c$ )	30* seconds <sup>[2]</sup>
<b>Ramp-down rate (<math>T_p</math> to <math>T_L</math>)</b>	6 °C/second max.
Time 25 °C to peak temperature	8 minutes max.

\* [1]  $T_c=260^{\circ}\text{C}$ .

\* [2] The time above 255 °C must not exceed 30 seconds.

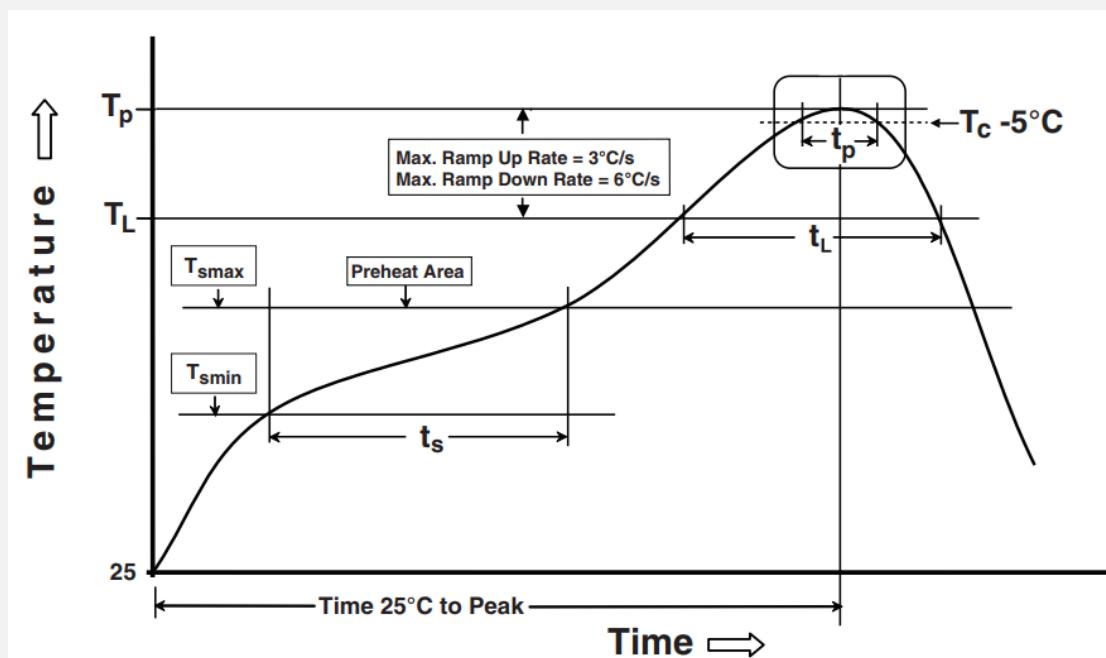


Figure 9 Reflow soldering profile (Refer to IPC/JEDEC J-STD-020E)

## 7 PRODUCT PACKAGING AND HANDLING

### 7.1 Packaging

#### 7.1.1 Packaging Notes

TAU1105 GNSS module is a Moisture Sensitive Device (MSD) and Electrostatic Sensitive Device (ESD). During the packing and shipping, it is strictly required to take appropriate MSD handling instructions and precautions. The table below shows the general packing hierarchy for the standard shipment.

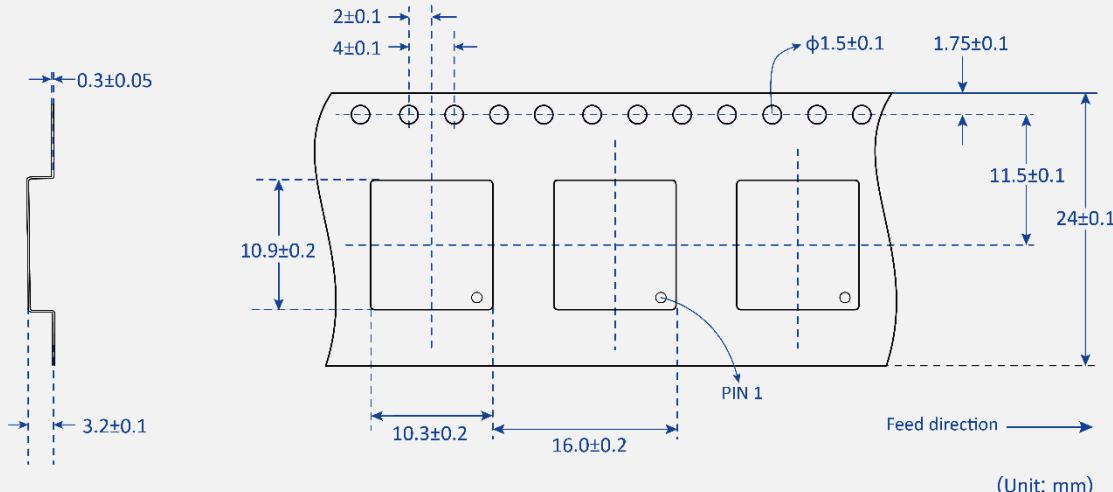
**Table 12 Packing hierarchy**

Module	Reel	Sealed bag	Shipping carton
			

**Note:** Packaging of non-standard quantities is not explained here. Take the reality as a reference.

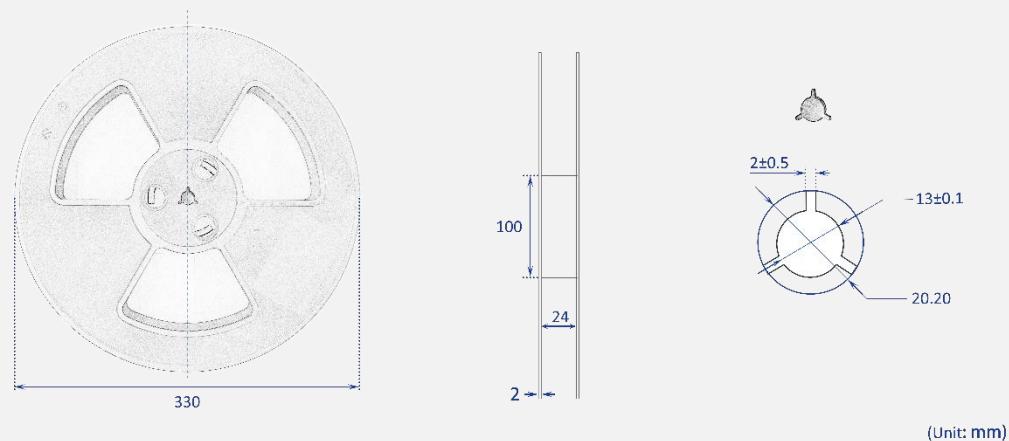
#### 7.1.2 Tape and Reel

The TAU1105 modules are delivered as hermetically sealed, reeled tapes in order to enable efficient production, production lot set-up and tear-down. The figure below shows the tape dimension.



**Figure 10 Tape dimensions**

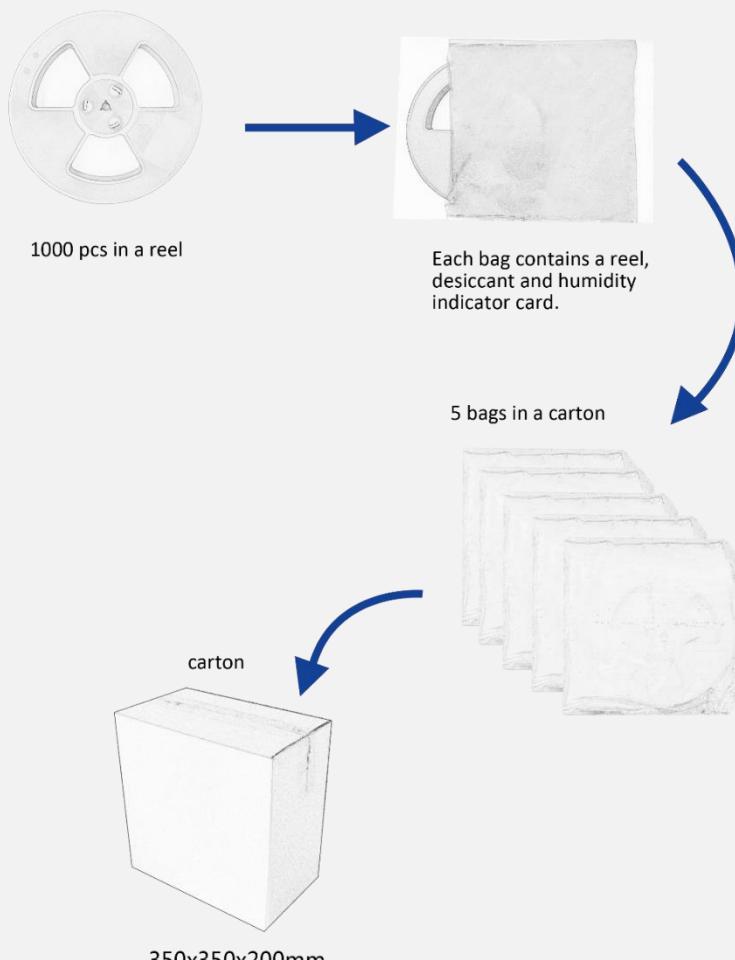
TAU1105 modules are deliverable in quantities of 1000pcs on a reel. The figure below shows the dimensions of reel for TAU1105.



**Figure 11 Reel dimensions**

### 7.1.3 Shipment Packaging

The reels of TAU1105 modules are packed in the sealed bags and shipped by shipping cartons. Up to five sealed bags (5000pcs in total) can be packed in one shipping carton.



**Figure 12 Packaging**

## 7.2 Storage

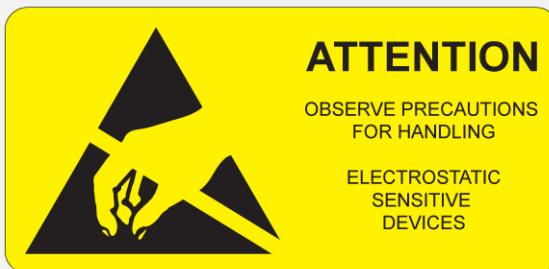
In order to prevent moisture intake and protect against electrostatic discharge, TAU1105 is packaged together with a humidity indicator card and desiccant to absorb humidity.

## 7.3 Handling

### 7.3.1 ESD Handling Precautions

TAU1105 module which contains highly sensitive electronic circuitry is an Electrostatic Sensitive Device (ESD). Observe precautions for handling! Failure to observe these precautions may result in severe damage to the GNSS module!

- Unless there is a galvanic coupling between the local GND (i.e. the workbench) and the PCB GND, then the first point of contact when handling the PCB must always be between the local GND and PCB GND.
- Before mounting an antenna patch, connect ground of the device.
- When handling the RF pin, do not come into contact with any charged capacitors and be careful when contacting materials that can develop charges (e.g. patch antenna ~10 pF, coax cable ~50 – 80 pF/m, soldering iron...)
- To prevent electrostatic discharge through the RF input, do not touch any exposed antenna area. If there is any risk that such exposed antenna area is touched in non ESD protected work area, implement proper ESD protection measures in the design.
- When soldering RF connectors and patch antennas to the receiver's RF pin, make sure to use an ESD safe soldering iron (tip).



### 7.3.2 ESD Protection Measures

The GNSS positioning module is sensitive to static electricity. Whenever handling the module, particular care must be exercised to reduce the risk of electrostatic charges. In addition to standard ESD safety practices, the following measures should be taken into account.

- Add ESD Diodes to the RF input part to prevent electrostatics discharge.
- Do not touch any exposed antenna area.
- Add ESD Diodes to the UART interface.

### 7.3.3 Moisture Sensitivity Level

The Moisture Sensitivity Level (MSL) of the GNSS module is MSL3.

## 8 REVISION HISTORY



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